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Project number:  
Dealer name:  
Dealer reference:  
Dealer contact person:  
Offer subject:  
Offered by:

Machine type: Cabinet motor on\_off + servo control [01] 1.6A SSW [3P400V+N+PE\_50Hz]  
Machine series: HortiMaX-Go!  
Machine number: 20820321  
Machine nominal supply voltage: [3x400V+N+PE/50Hz]  
Machine nominal supply current:  
Machine connected load:  
Machine cos phi:  
Machine maximum pre-fuse:

Corporation name:  
Corporation address:  
Postal code:  
Domicile/city:  
Region:  
Country:  
Contact person:  
Telephone number:

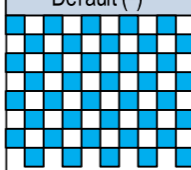
Project name: 20820321EAS020 Cabinet motor on\_off + servo control [01] 1.6A SSW [3P400V+N+PE\_50Hz]  
Project status: [As Build]  
Project template: 20820321EAS011 Cabinet motor on\_off + servo control [01] 1.6A SSW [3P400V+N+PE\_50Hz]  
Project initial date: 01/01/2024  
Project designed by: MBL  
Document number: 20820321EAS020  
Page number: 1  
Number of pages: 10

Notice 1: [ETO]  
Notice 2:  
Notice 3:

NEN-EN-IEC 60204-1:2006

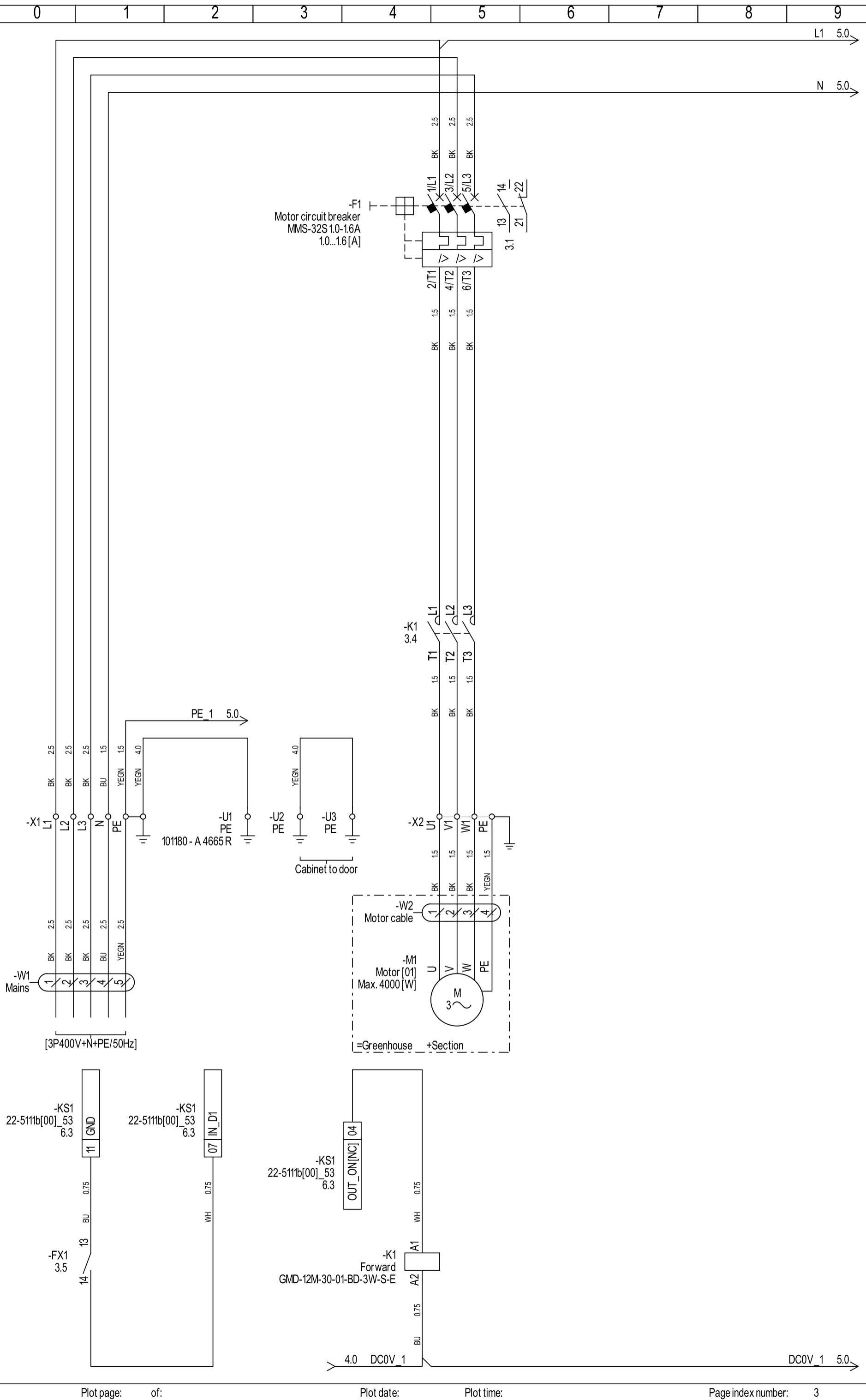
Color	Abbreviation	Power circuit
Black	BK	Mains voltage phase
Blue	BU	Mains voltage null
Yellow/green	YEGN	Ground [Systeem ground]
Control circuit		
Red	RD	Control circuit DC24V plus
Blue	BU	Control circuit DC24V min
White	WH	Control circuit DC24V switched
Brown	BN	Control circuit AC24V phase
Yellow	YE	Control circuit AC24V null
Grey	GY	Control circuit AC24V switched
Alarm circuit		
Orange	OG	Signaling and alarm

Wire gauge designation in [mm²]

Default (-)	Originating from page	Optional (-)
		



Project file: 20820321EAS020 Cabinet motor on_off + servo control [01] 1.6A SSW [3P400V+N+PE_50Hz]	Page initial date: 01/01/2024	Symbol scale: 1:1	Page: 2
Project number: 20820321EAS020	Function (-): =Unit	Project initial date: 01/01/2024	Page designed by: MBL
URL: http://www.Ridder.com	Location (+): +Main cabinet	Project designed by: MBL	Page revision date:
Document number: 20820321EAS020	Product (-): -Standards	Project status: [As Build]	Page revision:
		Drawing scale: 1:1	of: 10
			Page index:



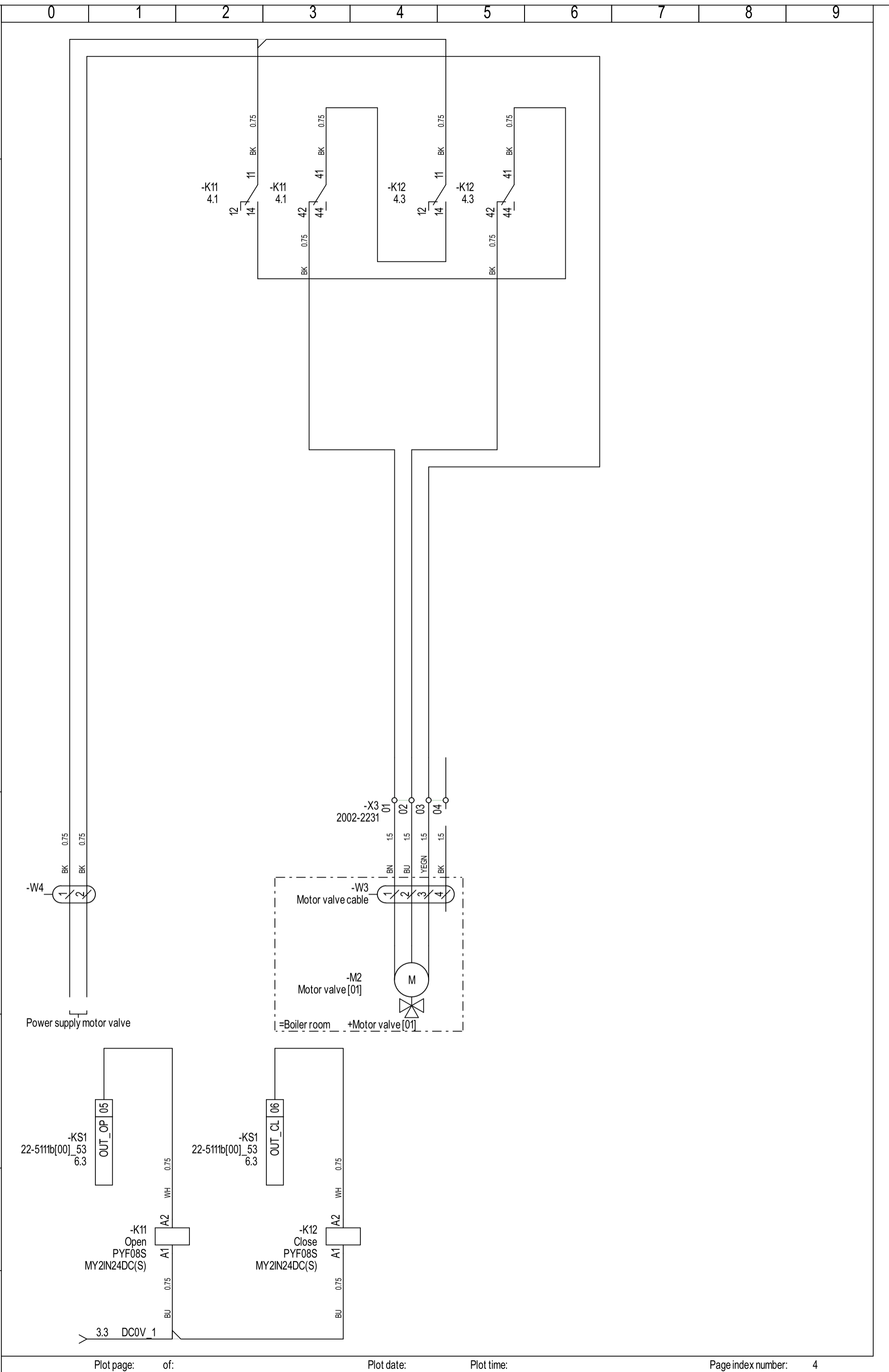


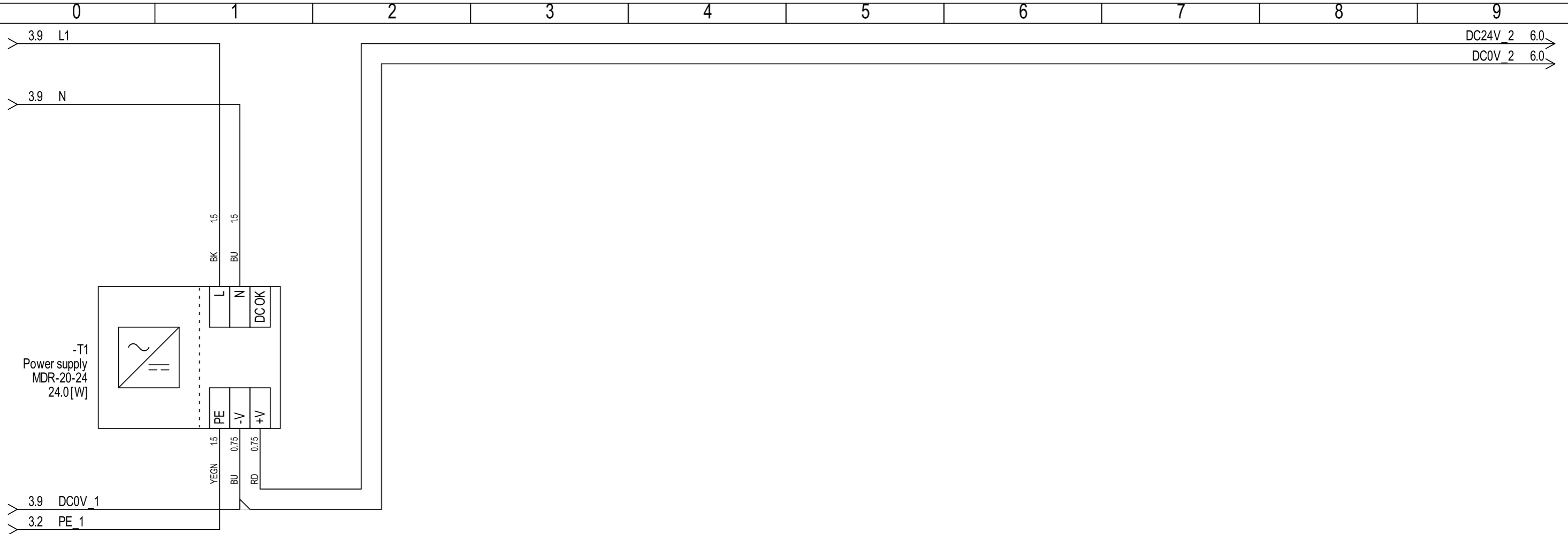
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 Document number: 2082032IEAS020

Function (-): =Unit  
 Location (+): +Main cabinet  
 Product (-): -Motor valve

Project initial date: 01/01/2024  
 Project designed by: MBL  
 Project status: [As Build]

Page initial date: 01/01/2024  
 Page designed by: MBL  
 Page revision date:  
 Page revision:





Page index number: 5

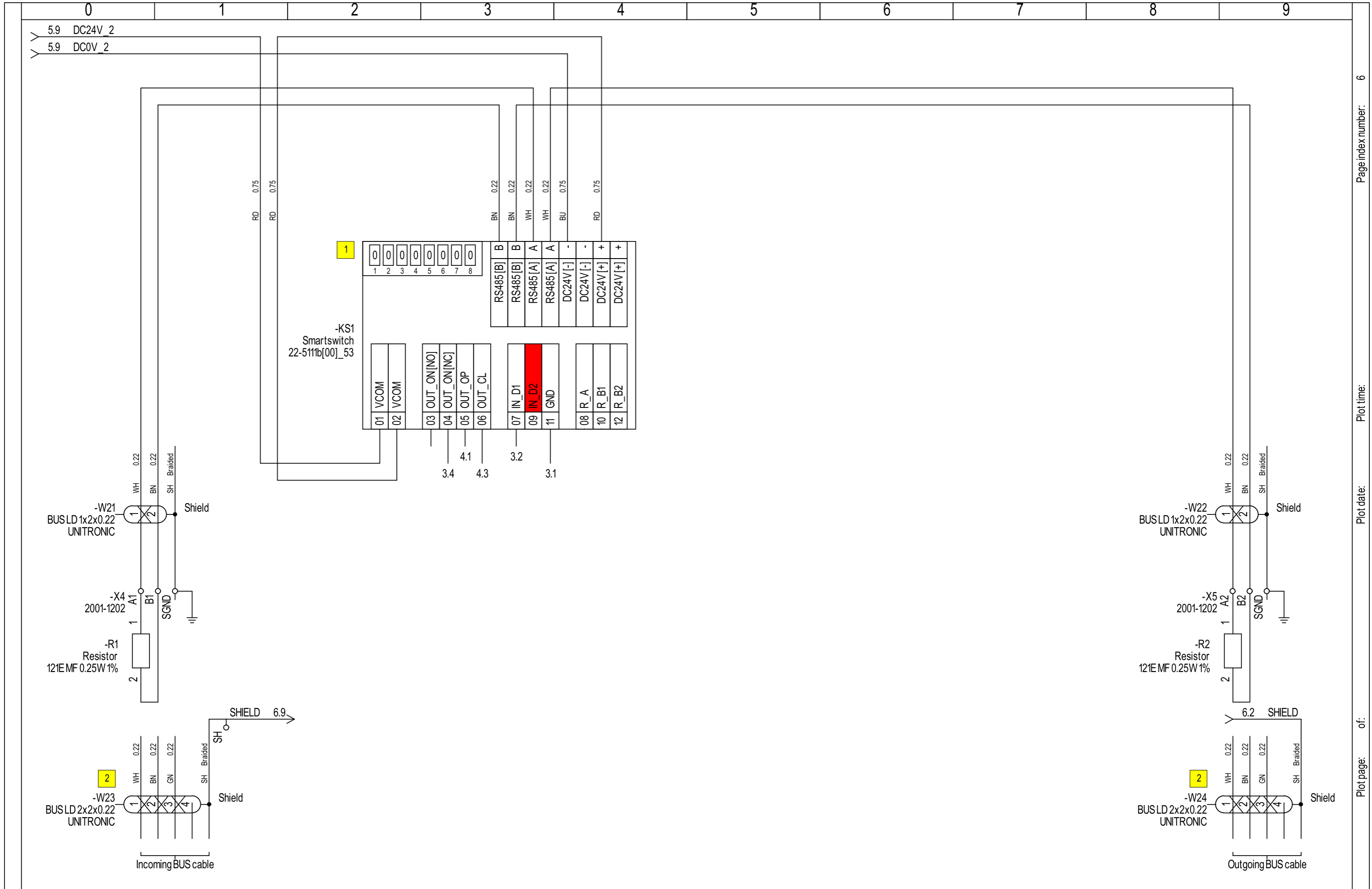
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of: Plot page:



Project file:	20820321EAS020 Cabinet motor on_off + servo control [01] 1.6A SSW [3P400V+N+PE_50Hz]		Page initial date:	01/01/2024	Symbol scale:	1:1	Page:	5			
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URL:	http://www.Ridder.com		Location (+):	+Main cabinet		Project designed by:	MBL		Page revision date:		Page index:
Document number:	20820321EAS020		Product (-):	-Control power		Project status:	[As Build]		Page revision:		



Project file:	20820321EAS020 Cabinet motor on_off + servo control [01] 1.6A SSW [3P400V+N+PE_50Hz]	Page initial date:	01/01/2024	Symbol scale:	1:1	Page:	6
Project number:		Function (-):	=Unit	Project initial date:	01/01/2024	Page designed by:	MBL
URL:	http://www.Ridder.com	Location (+):	+Main cabinet	Project designed by:	MBL	Page revision date:	
Document number:	20820321EAS020	Product (-):	-Smartswitch [KS1]	Project status:	[As Build]	Page revision:	
						Drawing scale:	1:1
						of:	10
						Page index:	

Customer inquiry [1] - Power rating of controlled motor(s)

1	What is the power rating of the motor(s) the customer wants to control with the cabinet.
	The power rating of a controlled motor determines the rating of the motor circuit breaker. What is the power rating of the controlled motor(s)? What is the rating of the applied motor circuit breaker(s)? Register this in the tables below.

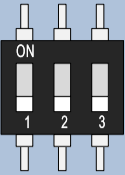
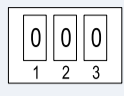
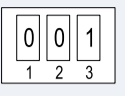
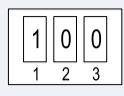
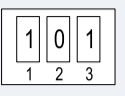
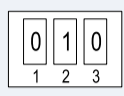
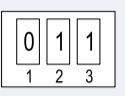
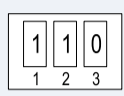
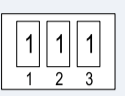
-	Motor	Power rating motor [W]
	[M]	[W]

#	Product code	Applied motor circuit breakers	3-phase [W] [400V_50/60Hz] max.
	32510061	Motor circuit breaker MMS-32S 0.4-0.63A	120 [W]
	32510101	Motor circuit breaker MMS-32S 0.63-1.0A	250 [W]
1	32510161	Motor circuit breaker MMS-32S 1.0-1.6A	550 [W]
	32510251	Motor circuit breaker MMS-32S 1.6-2.5A	750 [W]
	32510401	Motor circuit breaker MMS-32S 2.5-4.0A	1500 [W]
	32510631	Motor circuit breaker MMS-32S 4.0-6.0A	2200 [W]
	32510800	Motor circuit breaker MMS-32S 5.0-8.0A	3000 [W]
	32511001	Motor circuit breaker MMS-32S 6.0-10.0A	4000 [W]

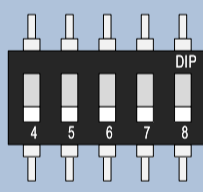
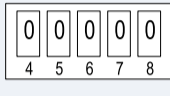
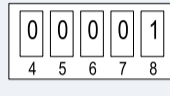
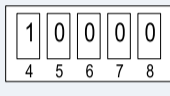
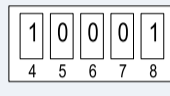
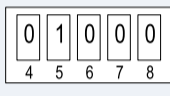
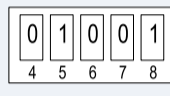
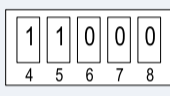
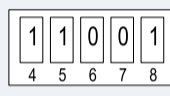
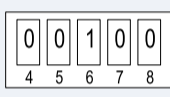
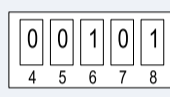
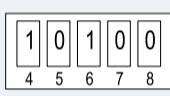
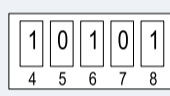
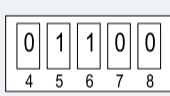
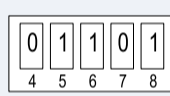
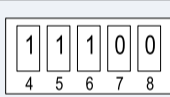
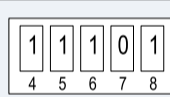
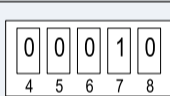
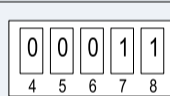
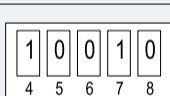
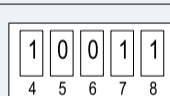
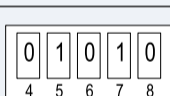
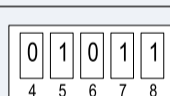
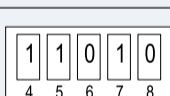
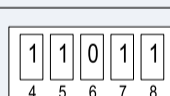
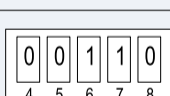
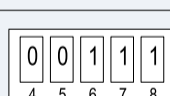
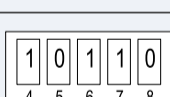
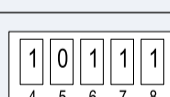



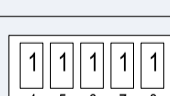
Procedure [1] - Addressing Smartswitches within the BUS-system

1	Set the section number for all Smartswitches within the BUS-system.
A	The section number is digitally composed with DIP-switches [1..3], of which DIP-switch [1] is the [Least Significant Bit], and DIP-switch [3] is the [Most Significant Bit].
1	Set the sequence number for all Smartswitches within the BUS-system.
B	The Smartswitch sequence number is digitally composed with DIP-switches [4..8], of which DIP-switch [4] is the [Least Significant Bit], and DIP-switch [8] is the [Most Significant Bit].
1	Remarks
C	The address of a Smartswitch; DIP-switches [1..8] has to be unique within the BUS-system. A Smartswitch of type [20800400 Smartswitch 24-5103b[00]_0 Alarm+meteo] always needs to be present within a BUS-system. This Smartswitch always needs to be addressed as [000 00000].

Section number - DIP-switch [1..3]

	Section 1		Section 5	
	Section 2		Section 6	
	Section 3		Section 7	
	Section 4		Section 8	

Smartswitch sequence number - DIP-switch [4..8]

	00		16	
	01		17	
	02		18	
	03		19	
	04		20	
	05		21	
	06		22	
	07		23	
	08		24	
	09		25	
	10		26	
	11		27	
	12		28	
	13		29	
	14		30	
	15		31	



Procedure [2] - Connecting cabinets within the BUS-system

2	General specifications RS485 network
A	<p>Cabinets in the network are connected in series.</p> <p>Stubs of the transmission line are not allowed.</p> <p>The [A] and [B] signals are transmitted over a twisted-pair.</p> <p>The [SGND] (Signal Ground) of the different cabinets are connected to one another over one wire of a twisted pair.</p> <p>The [SGND] in a cabinet is connected to [PE] of that cabinet.</p> <p>The [SH] (Cable Shield) is ONLY connected to [PE] in the controller cabinet.</p> <p>The cable shields of incoming and outgoing BUS-cables in Smartswitch cabinets are spliced together and are NOT connected to [PE].</p> <p>Both the outer ends of the network have to be terminated with a 120 [Ohm] resistor.</p> <p>The maximum length of the RS485 BUS-cable in the installation is 1200 [m]. This length only applies when a suitable RS485 Bus-cable type is utilized in the installation.</p> <p>General specification for RS485 BUS-cable:</p> <ul style="list-style-type: none"> <li>• Suitable for bus systems based on RS485,</li> <li>• Twisted pair (s),</li> <li>• Shielded,</li> <li>• Characteristic impedance 120 [Ohm].</li> </ul> <p>Recommended cable types:</p> <ul style="list-style-type: none"> <li>32002810 Buskabel UNITRONIC BUS LD 2x2x0.22 100 [m]</li> <li>32002811 Buskabel UNITRONIC BUS LD 2x2x0.22 300 [m]</li> <li>32002812 Buskabel UNITRONIC BUS LD 2x2x0.22 500 [m]</li> <li>32002820 Buskabel UNITRONIC BUS LD 3x2x0.22 100 [m]</li> </ul>

Procedure [2] - Connecting cabinets within the BUS-system - Continued

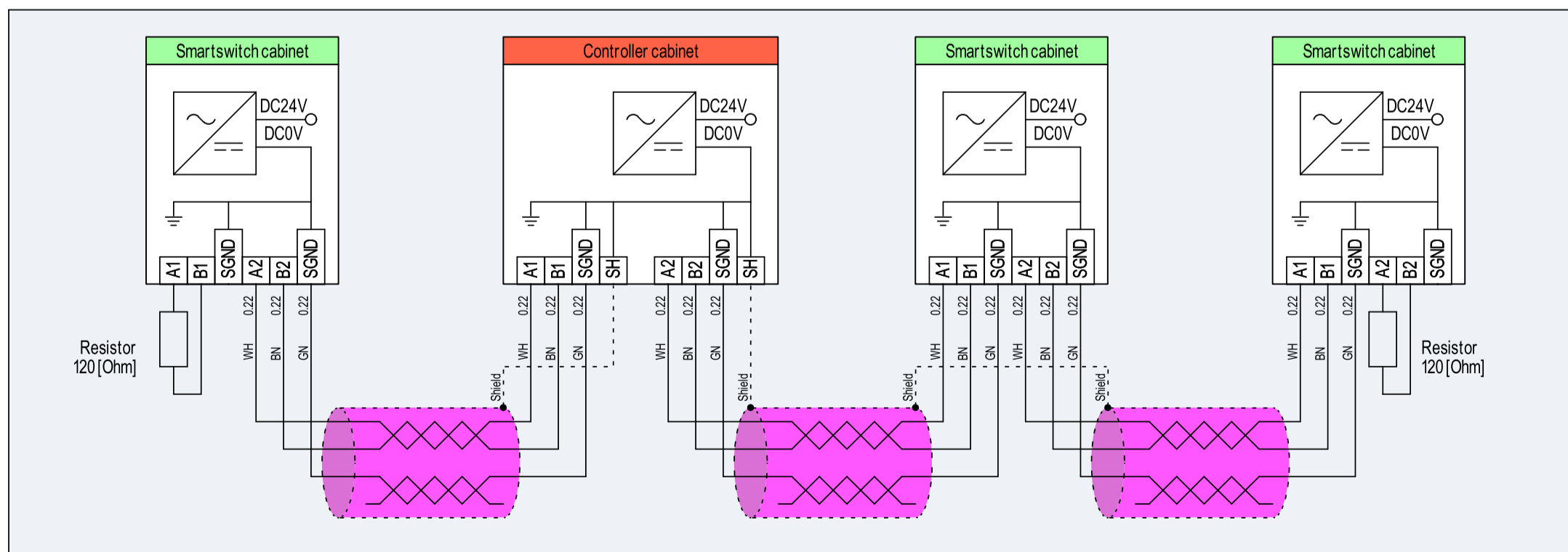
2	Connecting outgoing BUS-cable to Smartswitch cabinet
E	<p>Remove resistor [R2] currently connected to terminals [A2] and [B2].</p> <p>Connect twisted pair [1] wire [WH] to terminal [A2].</p> <p>Connect twisted pair [1] wire [BN] to terminal [B2].</p> <p>Connect twisted pair [2] wire [GN] to terminal [SGND].</p> <p>Splice the cable shield of the outgoing BUS-cable together with the cable shield of the incoming BUS-cable (when present) using a splice connector. When there is no incoming BUS-cable then isolate the shield of the outgoing BUS-cable, and leave it unconnected. A BUS-cable shield should only be connected to GND at ONE outer end of that cable; in the Controller cabinet.</p> <p>When there is no outgoing BUS-cable then leave resistor [R2] in place, connected to terminals [A2] and [B2].</p>

2	Connecting incoming BUS-cable to Controller cabinet
B	<p>Remove Resistor [R1] currently connected to terminals [A1] and [B1].</p> <p>Connect twisted pair [1] wire [WH] to terminal [A1].</p> <p>Connect twisted pair [1] wire [BN] to terminal [B1].</p> <p>Connect twisted pair [2] wire [GN] to terminal [SGND].</p> <p>Connect cable shield to terminal [SH].</p> <p>When there is no incoming BUS-cable then leave resistor [R1] in place, connected to terminals [A1] and [B1].</p>

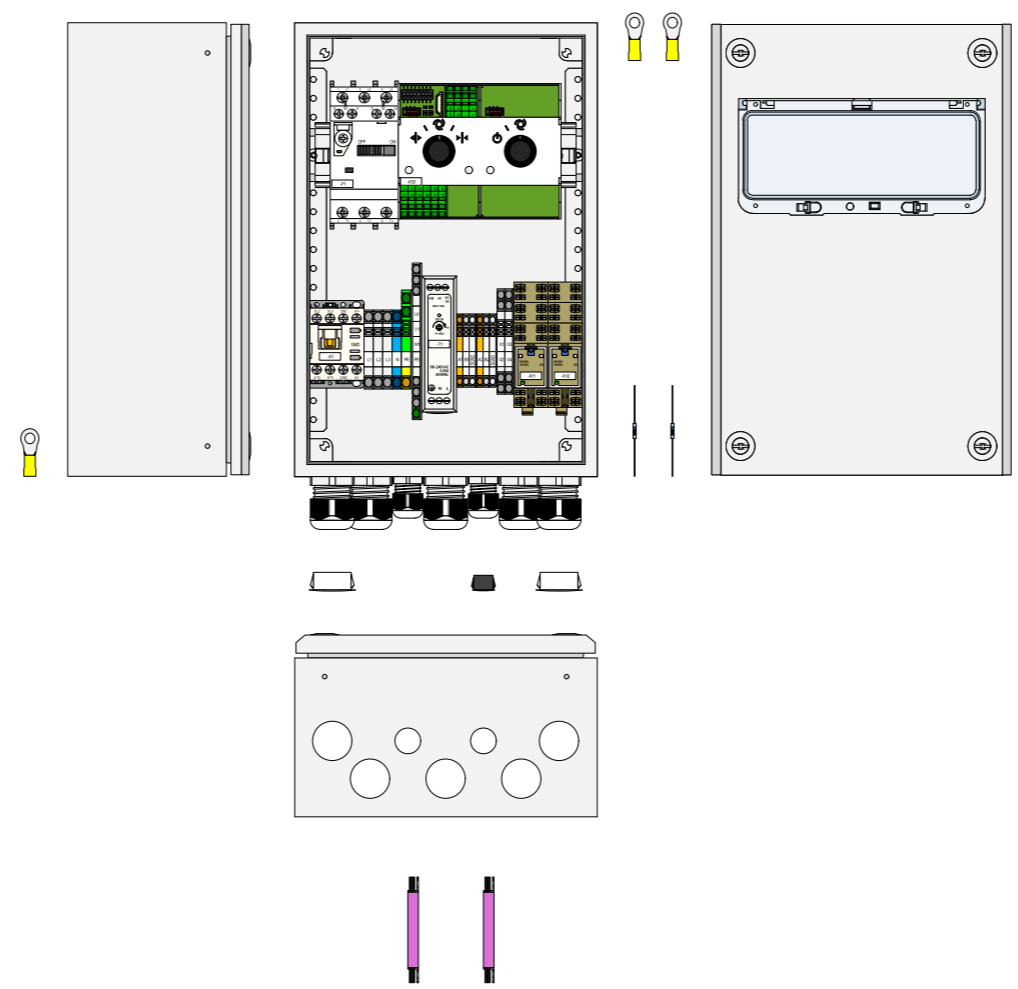
2	Connecting outgoing BUS-cable to Controller cabinet
C	<p>Remove resistor [R2] currently connected to terminals [A2] and [B2].</p> <p>Connect twisted pair [1] wire [WH] to terminal [A2].</p> <p>Connect twisted pair [1] wire [BN] to terminal [B2].</p> <p>Connect twisted pair [2] wire [GN] to terminal [SGND].</p> <p>Connect cable shield to terminal [SH].</p> <p>When there is no outgoing BUS-cable then leave resistor [R2] in place, connected to terminals [A2] and [B2].</p>

2	Connecting incoming BUS-cable to Smartswitch cabinet
D	<p>Remove Resistor [R1] currently connected to terminals [A1] and [B1].</p> <p>Connect twisted pair [1] wire [WH] to terminal [A1].</p> <p>Connect twisted pair [1] wire [BN] to terminal [B1].</p> <p>Connect twisted pair [2] wire [GN] to terminal [SGND].</p> <p>Splice the cable shield of the incoming BUS-cable together with the cable shield of the outgoing BUS-cable (when present) using a splice connector. When there is no outgoing BUS-cable then isolate the shield of the incoming BUS-cable, and leave it unconnected. A BUS-cable shield should only be connected to GND at ONE outer end of that cable; in the Controller cabinet.</p> <p>When there is no incoming BUS-cable then leave resistor [R1] in place, connected to terminals [A1] and [B1].</p>

Network topology



VERIFICATIE TABEL			
NO	VERIFICATIE	VERIFICATIE	VERIFICATIE
1			●
2			●
3			●
4			●
5			●
6			●
7			●
8			●
9			●



Project file:	20820321EAS020 Cabinet motor on_off + servo control [01] 1.6A SSW [3P400V+N+PE_50Hz]		Page initial date:	01/01/2024	Symbol scale:	1:5	Page:	10
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URL:	http://www.Ridder.com	Location (+):	+Main cabinet	Project designed by:	MBL	Page revision date:		Page index:
Document number:	20820321EAS020	Product (-):	-Cabinet layout	Project status:	[As Build]	Page revision:		